

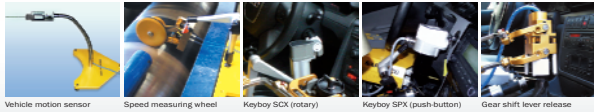
## Variations and options

### Variations

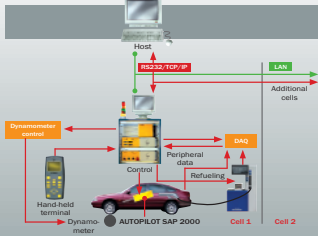
| SAP2000   | E | M | MP | ACT |
|---|---|---|----|-----|
| Accelerator                                       | + | + | +  | +   |
| Brake   | + | + | +  | +   |
| Clutch  | + | + | +  | +   |
| Gear shift arm left-hand drive                    | + | + | +  | +   |
| Gear shift arm right-hand drive                   | 0 | 0 | 0  | 0   |
| Gear shift arm steering-column shift              | 0 | 0 | 0  | 0   |
| Keyboy SBX/SCX (rotary) fail – safe               | + | 0 | 0  | 0   |
| Keyboy SPX (push-button) fail – safe              | 0 | 0 | 0  | 0   |
| Pedal touch detection switch accelerator & brake  | + | 0 | -  | -   |
| Adapter for steering-column shift N - D           | 0 | 0 | 0  | 0   |
| Actuator for steering wheel paddle +/- shifting   | 0 | 0 | 0  | 0   |
| Steering actuator systems                         | 0 | 0 | 0  | 0   |
| Safety brake actuator systems                     | 0 | 0 | 0  | 0   |
| Gear shift lever release                          | 0 | 0 | 0  | 0   |
| Gear shift force measurement & control            | 0 | 0 | 0  | 0   |
| Truck adapter                                     | 0 | 0 | 0  | 0   |
| Hand-held terminal                                | + | + | +  | +   |
| Universal vehicle self-learn cycle (basic)        | + | + | +  | +   |
| Universal vehicle self-learn cycle with Auto tune | + | + | -  | -   |
| Human drive style speed control                   | + | + | -  | -   |
| Selectable human drive styles                     | + | + | -  | -   |
| Manual driving mode                               | + | + | +  | +   |
| Manual Set-point mode                             | + | + | +  | +   |
| Braking via chassis dynamometer                   | + | + | +  | +   |
| Road gradient output to chassis dynamometer       | + | + | -  | -   |
| Data acquisition & Graphic cycle protocol         | + | + | +  | +   |
| Hybrid & Fuel Cell & electric engine support      | + | + | +  | +   |
| Stop & Start engine support                       | + | + | +  | +   |
| WINDOWS user interface WIN32                      | + | + | +  | +   |
| Analog inputs for MAP / tractive effort           | + | + | +  | -   |
| Adapter for seat rail mounting                    | + | + | +  | +   |

E: emission test  
M: mileage accumulation / durability testing  
MP: mileage accumulation with PID controller  
ACT: actuator

+ standard  
0 optional  
- not possible



Vehicle motion sensor    Speed measuring wheel    Keyboy SCX (rotary)    Keyboy SPX (push-button)    Gear shift lever release



### Optional hardware

- Shift arm for full - range column shifting
- RHD and LHD shift actuators
- Dash board shifter set
- Shift release mechanism
- Push/Pull actuator for shift lever
- Shift unlock / release actuators
- Shift Force measurement
- Pedal force measurement
- 2-axis push-button actuator for steering wheel +/- and paddle shift actuation
- Truck adapter set
- Truck Range select and splitter gear select actuation
- Ignition key actuators: Keyboys for rotary or push-button style ignition keys
- Universal push-button actuators
- Steering actuators
- Safety brake actuators
- Seat rail mounting device
- Autonomous driving package for driving on proving grounds
- Vehicle motion sensor



Seat rail adapter    Full range column shifter

### Optional system interfaces

- Host computer interface: Extended AK protocol - serial / TCP/IP
- Hybrid bit - parallel & analog interface
- Fieldbus interface to vehicle on-board data through OBD / CAN interface
- Fieldbus Interface to chassis dyno for LifeData exchange
- Fieldbus Interface to data acquisition system
- Interface to refueling system for refueling process defined by cycle and fuel tank level
- UDP or OPC Server/Client interface
- Customized interfaces on request

## Company portrait + Product range

### Company portrait

STÄHLE GmbH was founded in 1987. It is a high-performance family-run enterprise with CAM-supported CNC machines. Development of hardware and software goes on at the engineering offices of Ing. Büro Kurt Stähle. Design work is performed at 3D-CAD work stations with FE optimization. We see ourselves as being conservative only in the sense of being obligated to our customers to be a competent and reliable partner.

### Further products



Autonomous driving package

05/2009, Technical modifications reserved

Represented by:

**STÄHLE**

# Autopilot System

**SAP2000**

for computer controlled driving of cars on test stands

*precise - reliable - efficient*



- Human drive style speed control
- Different human drive styles selectable
- Extrem high repeatability
- Very fast and simple vehicle installation
- Dynamic and accurate actuator and drive system
- For M/T and A/T vehicles
- For combustion engine – hybrid – fuel cell – electric powered vehicles

**STÄHLE**  
ROBOT SYSTEMS

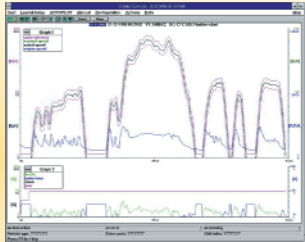
**STÄHLE Robot Drivers –**  
*in use world-wide.*

STÄHLE GmbH · Maybachstraße 12 · D-71299 Wimsheim · Germany  
Tel. +49 (0)70 44-9 15 61-0 · Fax +49 (0)70 44-9 15 61-29  
Internet: [www.staehle.com](http://www.staehle.com) · Email: [info@staehle.com](mailto:info@staehle.com)

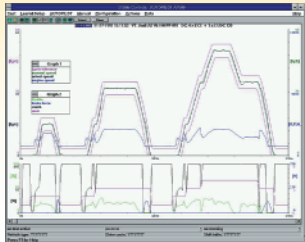
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## Objective measuring procedure = clear results



FTP/EPA emissions cycle, generated by STÄHLE AUTOPILOT

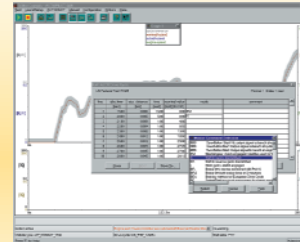


ECE emissions cycle, generated by STÄHLE AUTOPILOT

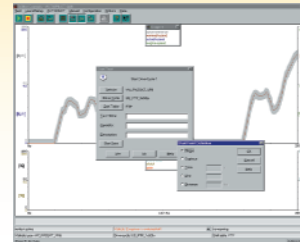


The ideal robot test driver for research, development and quality control

## AUTOPILOT SAP 2000 for computer-controlled driving on chassis dynamometers



Programming driving cycles



Selecting starting point

## Features + technical specifications

### Features

- Stand-alone system
- Can be installed on the driver's seat without any modification to the vehicle (approx. 8 min.)
- Hardware and software designed for one-man operation
- Self-learning function in special selflearn cycle
- Constant control behavior during tests
- Mechanism designed for continuous operation and any climate
- Automatic compensation for installation tolerances between robot and accelerator pedal
- Continuous learning of the clutch bite point when clutch is released during start-up (compensates for clutch wear)
- Highest safety standards:
  - Without power
    - Clutch pedal is depressed
    - Accelerator pedal is released
- Driving style options
  - smooth • accurate • high-accurate

### Technical specifications Robot driver SAP2000

|                         |                 |
|-------------------------|-----------------|
| Total weight            | 30 kg approx.   |
| Component weight        | max. 16 kg      |
| Control voltage         | 24 V            |
| Working temperature     | -40° C...+80° C |
| Accelerator actuator    |                 |
| Actuation system        | electrical      |
| Stroke                  | max. 150 mm     |
| Force                   | max. 100 N      |
| Velocity                | max. 0.45m/s    |
| Brake actuator          |                 |
| Actuation system        | electrical      |
| Stroke                  | max. 150 mm     |
| Force                   | max. 350 N      |
| Velocity                | max. 0.3 m/s    |
| Clutch actuator         |                 |
| Actuation system        | electrical      |
| Stroke                  | max. 200 mm     |
| Force                   | max. 200 N      |
| Velocity                | max. 0.35 m/s   |
| Shift actuator          |                 |
| Actuation system        | electrical      |
| Shift Stroke (X-axis)   | max. 250 mm     |
| Lateral Stroke (Y-axis) | max. 200 mm     |
| Force                   | max. 250 N      |
| Velocity                | max. 0.6 m/s    |

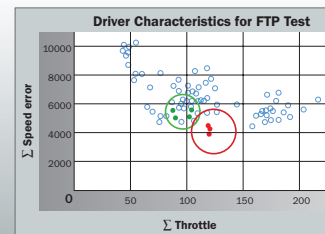
After many years of development work, the new generation of robot drivers – exemplified by the **AUTOPILOT SAP2000** – can take advantage of control software that has now fulfilled in reality what was once set up as visionary targets.

### Targets

- Human driving style with comparable emissions results
- High driving accuracy
- Selectable driving styles
- Ultra high reproducibility

### Reality

- The emission values are within the central cluster of the results obtained from test cycles driven by human drivers
- Typical driving accuracy is  $\leq 0,25$  km/h in "high-accurate" driving style mode
- Driving style options: smooth – accurate – high-accurate
- The typical distance error in an 11 kilometer driving cycle is  $\leq 2$  m



• various drivers • single driver • STÄHLE AUTOPILOT

### The AUTOPILOT SAP2000

can be linked to emission benches, chassis dynamometers and host computers. The drive mechanism is suitable for any climate and durability testing. Thus, the same mechanism can be used for a wide variety of testings without the necessity for modification.

- Emission measurements
- Acoustic measurements
- Durability testing mileage accumulation
- Transmission testing
- Calibration of engine control systems
- Climate measurements
- Correlation measurements
- Running-losses measurements

